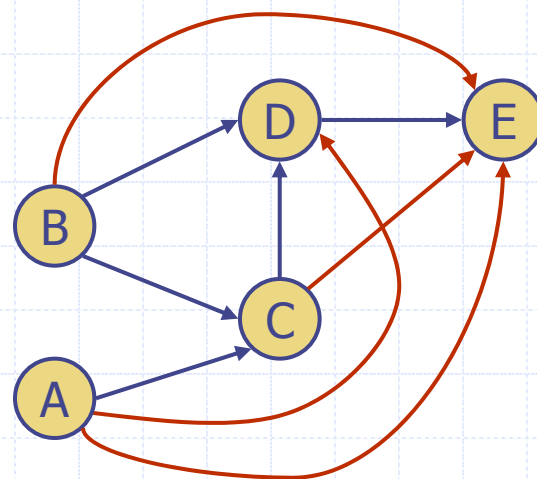


# Digraphs

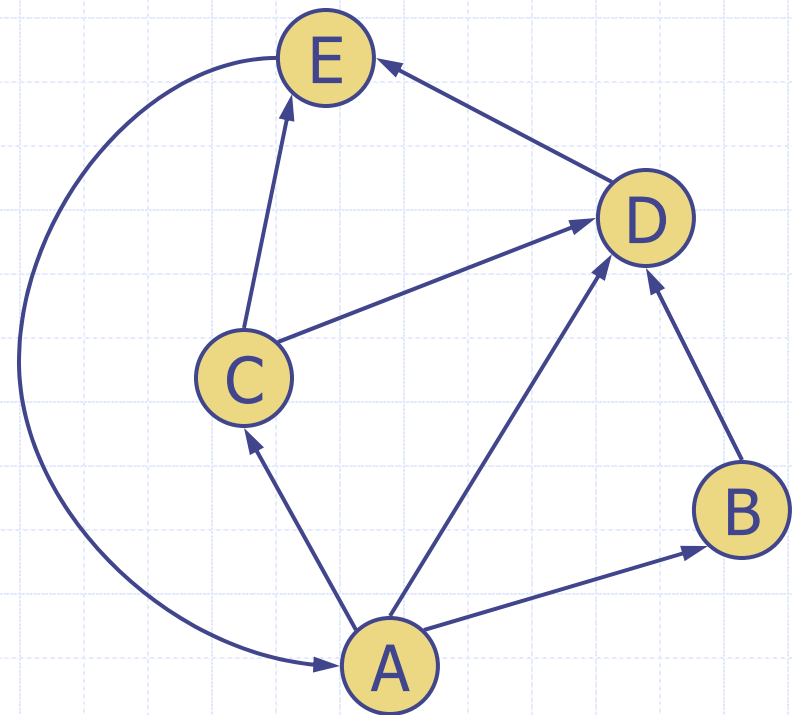


# Outline and Reading

- ◆ Digraphs (§13.4)
- ◆ Traversals of digraphs (§13.4.1)
- ◆ Transitive closure (§13.4.2)
- ◆ Floyd-Warshall's algorithm (§13.4.2)
- ◆ Directed acyclic graphs (§13.4.3)
- ◆ Topological ordering (§13.4.3)

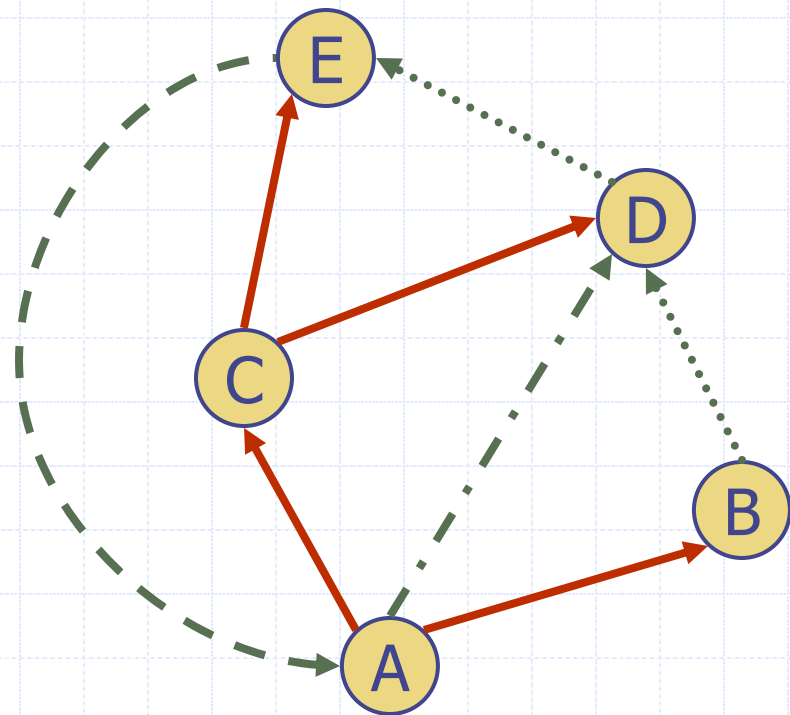
# Digraphs

- ◆ A digraph is a directed graph whose edges are all directed
- ◆ Applications
  - one-way streets
  - flights
  - task scheduling



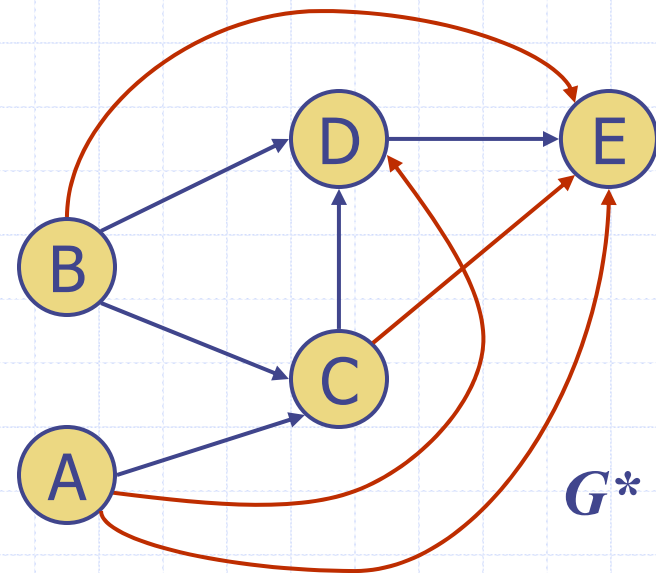
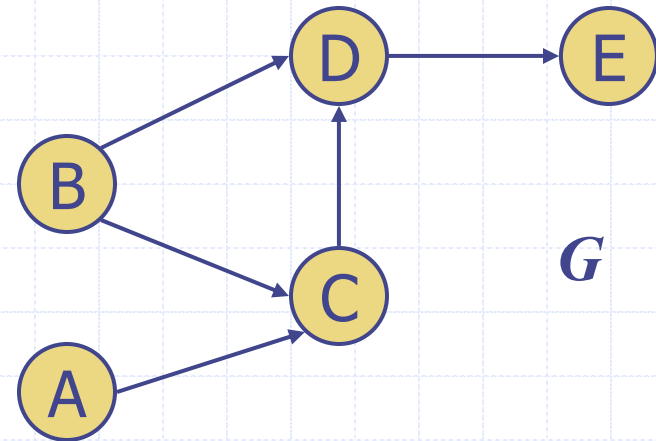
# Directed DFS

- ◆ We can specialize the traversal algorithms (DFS and BFS) to digraphs by traversing edges only along their direction
- ◆ In the directed DFS algorithm, we have four types of edges
  - discovery edges
  - back edges
  - forward edges
  - cross edges
- ◆ A directed DFS starting at a vertex  $s$  determines the vertices reachable from  $s$



# Transitive Closure

- ◆ Given a digraph  $G$ , the transitive closure of  $G$  is the digraph  $G^*$  such that
  - $G^*$  has the same vertices as  $G$
  - if  $G$  has a directed path from  $u$  to  $v$  ( $u \neq v$ ),  $G^*$  has a directed edge from  $u$  to  $v$
- ◆ The transitive closure provides reachability information about a digraph
- ◆ We can compute the transitive closure in time  $O(n(n + m))$  by repeated applications of directed DFS



# Floyd-Warshall's Algorithm

- ◆ Floyd-Warshall's algorithm numbers the vertices of a digraph  $G$  as  $v_1, \dots, v_n$  and computes a series of digraphs  $G_0, \dots, G_n$ 
  - $G_0 = G$
  - $G_k$  has a directed edge  $(v_i, v_j)$  if  $G$  has a directed path from  $v_i$  to  $v_j$  with intermediate vertices in the set  $\{v_1, \dots, v_k\}$
- ◆ We have that  $G_n = G^*$
- ◆ In phase  $k$ , digraph  $G_k$  is computed from  $G_{k-1}$

**Algorithm** *FloydWarshall*( $G$ )

**Input** digraph  $G$

**Output** transitive closure  $G^*$  of  $G$

$i \leftarrow 1$

**for all**  $v \in G.vertices()$

denote  $v$  as  $v_i$

$i \leftarrow i + 1$

$G_0 \leftarrow G$

**for**  $k \leftarrow 1$  **to**  $n$  **do**

$G_k \leftarrow G_{k-1}$

**for**  $i \leftarrow 1$  **to**  $n$  ( $i \neq k$ ) **do**

**for**  $j \leftarrow 1$  **to**  $n$  ( $j \neq i, k$ ) **do**

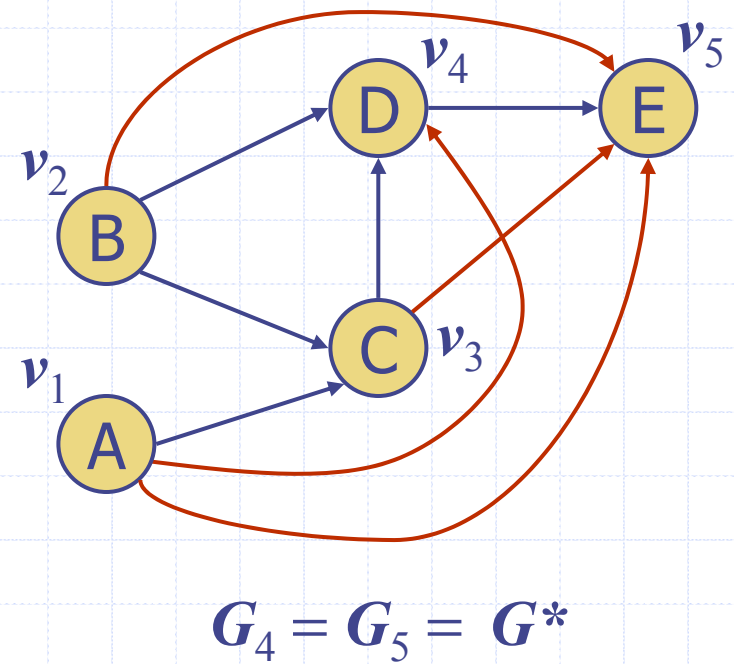
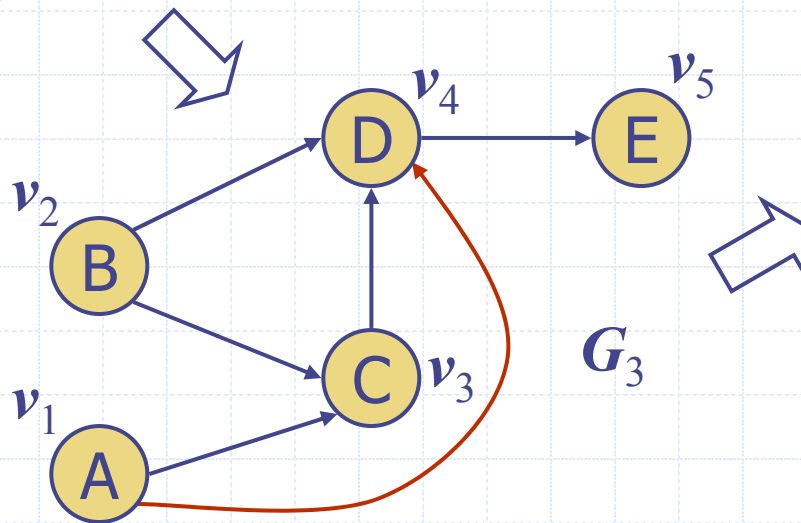
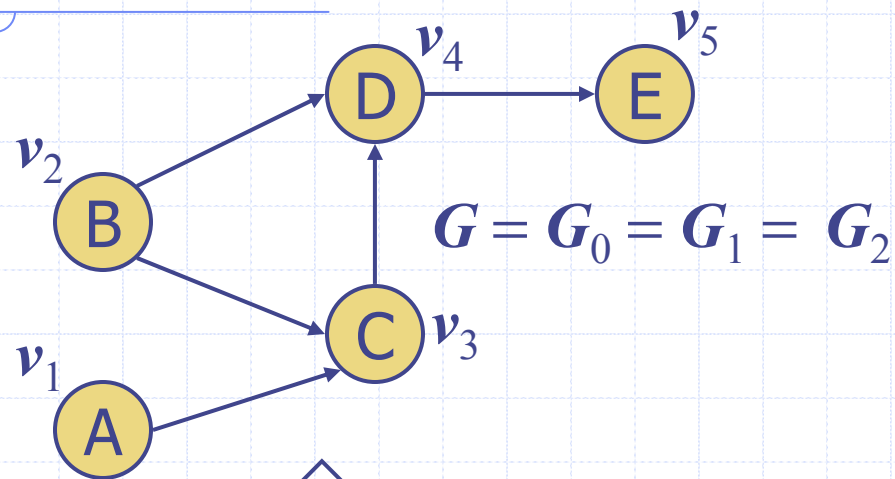
**if**  $G_{k-1}.areDirAdjacent(v_i, v_k) \wedge$   
 $G_{k-1}.areDirAdjacent(v_k, v_j)$

**if**  $\neg G_k.areDirAdjacent(v_i, v_j)$

$G_k.insertDirectedEdge(v_i, v_j, k)$

**return**  $G_n$

# Example



# DAGs and Topological Ordering

- ◆ A directed acyclic graph (DAG) is a digraph that has no directed cycles
- ◆ A topological ordering of a digraph is a numbering

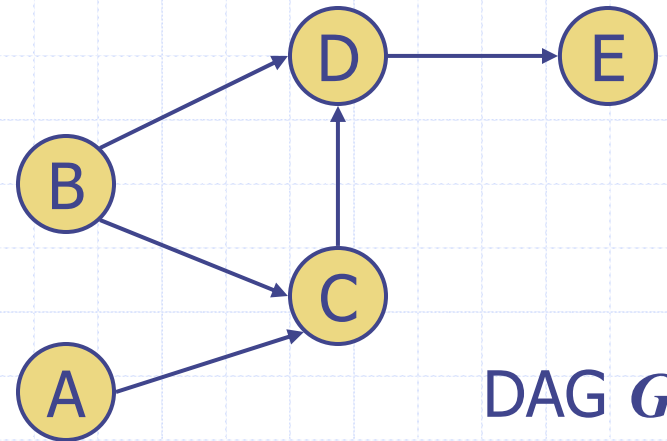
$$v_1, \dots, v_n$$

of the vertices such that for every edge  $(v_i, v_j)$ , we have  $i < j$

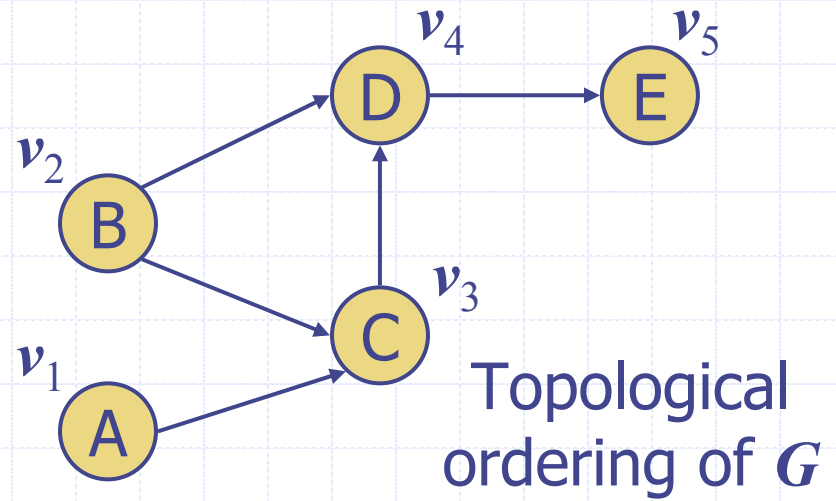
- ◆ Example: in a task scheduling digraph, a topological ordering a task sequence that satisfies the precedence constraints

## Theorem

A digraph admits a topological ordering if and only if it is a DAG



DAG  $G$



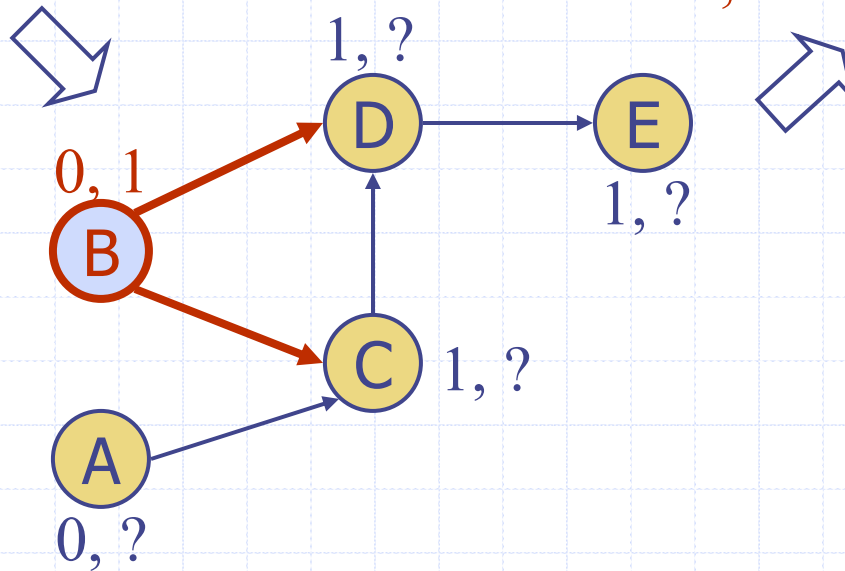
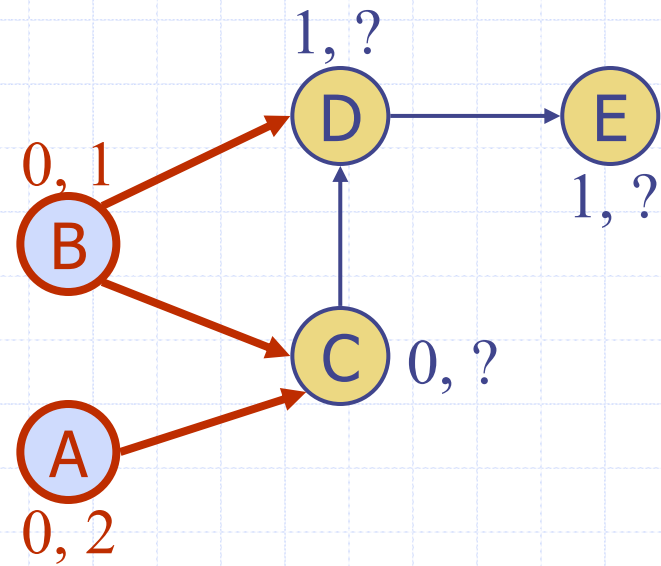
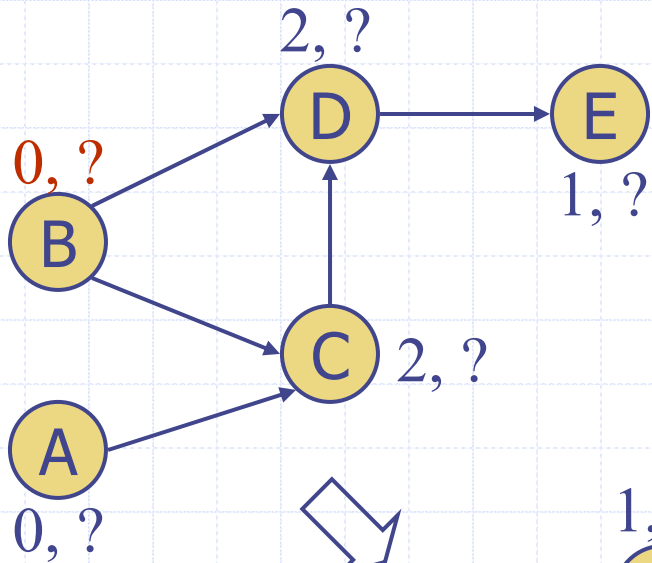
Topological ordering of  $G$

# Topological Ordering

- ◆ A stack stores the vertices whose predecessors have all been numbered
- ◆ We store two labels with each vertex:
  - Counter of predecessors not yet numbered
  - Rank in the topological ordering
- ◆ The algorithm runs in time  $O(n + m)$

```
Algorithm TopologicalOrdering(G)  
  S ← new stack  
  for all v ∈ G.vertices()  
    setCount(v, inDegree(v))  
    if getCount(v) = 0  
      S.push(v)  
  i ← 1  
  while ¬S.isEmpty()  
    u ← S.pop()  
    setRank(u, i)  
    i ← i + 1  
    for all e ∈ G.outgoingEdges(u)  
      z ← G.opposite(u, e)  
      setCount(z, getCount(z) - 1)  
      if getCount(z) = 0  
        S.push(z)
```

# Example



# Example

