

CSCI 1590  
Intro to Computational  
Complexity  
**PSPACE**-Complete Languages

John E. Savage

Brown University

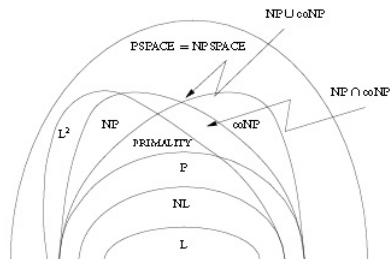
February 20, 2008

# Summary

- 1 Complexity Class Containment
- 2 Polynomial Time Hierarchy
- 3 **PH**-Complete Languages
- 4 Games and  $\text{TQBF}$
- 5  $\text{TQBF}$  is **PSPACE**-Complete

# Complexity Classes from Last Lecture

- **P**, **coNP**,
- $\Pi_i^P$  and  $\Sigma_i^P$
- **PH**
- **PSPACE**



# Polynomial Time Hierarchy

- A language is in **NP**(co**NP**) if and only if it can be reduced in polynomial time to a statement of the form  $\exists \mathbf{x} b(\mathbf{x})$  ( $\forall \mathbf{x} b(\mathbf{x})$ )
- By adding additional levels of quantification, as shown below, potentially new complexity classes are added.
  - $\forall \mathbf{x}_1 \exists \mathbf{x}_2 b(\mathbf{x}_1, \mathbf{x}_2)$
  - $\exists \mathbf{x}_1 \forall \mathbf{x}_2 b(\mathbf{x}_1, \mathbf{x}_2)$
- The sets of languages PTIME reducible to statements of this form are denoted  $\Pi_i^P$  and  $\Sigma_i^P$  respectively, when there are  $i$  alternations of existential and universal quantifiers and the outermost quantifier is  $\forall$  and  $\exists$ , respectively.

## Definition

The Polynomial Hierarchy (**PH**) is defined as

$$\mathbf{PH} = \bigcup_i \Sigma_i^P$$

# PH and PSPACE

## Definition

A language  $L$  is **PH-complete** if a)  $L \in \mathbf{PH}$  and b) all languages in **PH** are  $\text{PTIME}$  reducible to  $L$ .

- It is not hard to see that  $\mathbf{PH} \in \mathbf{PSPACE}$ .
- If a **PH**-complete language exists, the polynomial hierarchy collapses. (See last lecture.)

## Definition

TQBF denotes the family of quantified boolean formulas  $\Psi$  with an unbounded number of alternations that evaluate to True.

$$\Psi = Q_1 x_1 Q_2 x_2 \dots Q_n x_n \phi(x_1, x_2, \dots, x_n)$$

Here  $Q_j$  denotes either universal ( $\forall$ ) or existential ( $\exists$ ) quantification.

TQBF is an example of a **PSPACE**-complete language.

- Languages in **NP** are analogous to puzzles where we ask, “Is there a solution?”.
- By contrast, TQBF allows us to ask a seemingly harder question, “Is there a winning strategy?”. Player 1 can win if there is a choice for its variable such that for all choices by Player 2 there is a choice by Player 1, etc.
- In a game one player tries to account for all possible decisions that an opponent can make. Each level of alternation is like a single turn of the game.
- Unlike problems in **NP**, it does not appear that a certificate suffices to demonstrate membership in the class. Instead it seems necessary to provide the full set of alternatives implied by alternation of quantifiers.

# Outline of Proof that $TQBF$ is **PSPACE**-Complete

## Definition

$TQBF$  is **PSPACE**-complete if it is in **PSPACE** and every language  $L \in \mathbf{PSPACE}$  can be reduced to  $TQBF$  in polynomial time.

To show the second result, we use the following lemma on directed graphs.

## Lemma

*For  $G = (V, E)$  directed, let  $PATH_G(a, b, k)$  have value 1 (0) if  $\exists (\neg \exists)$  path from vertex  $a$  to vertex  $b$  in  $G$  of length  $\leq 2^k$ . (Used in Savitch's Theorem.) It can be described by a  $TQBF$  of length  $O(k\mu + |PATH_G(a, b, 0)|)$  where  $\mu$  and  $|PATH_G(a, b, 0)|$  are lengths of  $v \in V$  and formula that determines if  $b$  is reachable from  $a$  in one step.*

The following expansion of  $PATH_G(a, b, 2^k)$  is from Savitch's Theorem.

$$PATH_G(a, b, k) = \exists z PATH_G(a, z, k - 1) \wedge PATH_G(z, b, k - 1)$$

Expanding this gives length- $O(2^k |PATH_G(a, b, 0)|)$  instance of  $TQBF$ .

# Reducing PATH Predicate to TQBF Efficiently

To avoid expanding both  $\text{PATH}_G(a, z, k - 1)$  and  $\text{PATH}_G(z, b, k - 1)$ , restate the expansion of  $\text{PATH}_G(a, b, k)$  as shown below where  $p(u, v, a, z, b) \equiv (((u = a) \wedge (v = z)) \vee ((u = z) \wedge (v = b)))$ .

$$\text{PATH}_G(a, b, k) \equiv \exists z \forall (u, v) p(u, v, a, z, b) \Rightarrow \text{PATH}_G(u, v, k - 1)$$

Equality ( $u = v$ ) and implication ( $u \Rightarrow v$ ) can be expressed as the Boolean formulas  $(u \wedge v) \vee (\bar{u} \wedge \bar{v})$  and  $(\bar{u} \vee v)$ , respectively, giving

$$\text{PATH}_G(a, b, k) \equiv \exists z \forall (u, v) (\bar{p}(u, v, a, z, b) \vee \text{PATH}_G(u, v, k - 1))$$

Notice that  $\bar{p}(u, v, a, z, b)$  has  $16\mu$  literals where  $\mu$  is the number of Boolean variables used to represent each of  $u, v, a, z, b$  as a binary tuple.

Applying the expansion to  $\text{PATH}_G(u, v, k - 1)$  introduces two more quantifiers, increases the number of literals by  $16\mu$ , and expresses the result in terms of  $\text{PATH}_G(u, v, k - 2)$ . The hypothesis follows.

## Theorem

TQBF is **PSPACE-Complete**

## Proof

We show that TQBF is in **PSPACE**

$$\Psi = Q_1 x_1 Q_2 x_2 \dots Q_n x_n \phi(x_1, x_2, \dots, x_n)$$

To show this, note that  $\Psi$  is the OR of  $\Psi|_{x_1=1}$  and  $\Psi|_{x_1=0}$  when  $Q_1 = \exists$  whereas it is the AND when  $Q_1 = \forall$ . Systematically run through all assignments to variables. For each assignment, evaluate a copy of the original  $\phi(x_1, x_2, \dots, x_n)$ . If  $\phi(x_1, x_2, \dots, x_n)$  uses space  $m$ , this execution consumes space  $O(n + m)$ .

## Proof (cont.)

As shown in the Lemma, an instance of  $\text{PATH}_G(a, b, k)$  can be translated into an instance of TQBF of length  $O(k + |\text{PATH}_G(a, b, 0)|)$ .

As in Savitch's Theorem, we now show that any language  $L \in \mathbf{PSPACE}$  recognized by  $M$  can be reduced in PTIME to an instance of  $\text{PATH}_G(a, b, k)$  such that  $k$  and  $|\text{PATH}_G(a, b, 0)|$  are polynomial in the input  $\mathbf{x}$ . This provides a PTIME reduction from  $L$  to TQBF.

Let  $G$  be config. graph  $G$  of  $M$  on input  $\mathbf{x}$  with start and accept configs.  $C_{start}$  and  $C_{accept}$  (to ensure  $C_{accept}$  is unique, modify  $M$  so it erases its tape after accepting).  $\mathbf{x}$  is in  $L \Leftrightarrow C_{accept}$  is reachable from  $C_{start}$ .

$k = O(S(n))$  because there are  $O(c^{S(n)})$  configs. in  $G$ ,  $c$  a constant.  $|\text{PATH}_G(a, b, 0)|$  is polynomial in  $S(n)$  because there is a DTM that can recognise the language  $\text{PATH}_G(a, b, 0)$ . Since it is in  $\mathbf{P}$ , it can be reduced to an instance of SAT of polynomial length in  $S(n)$ .