

## Homework 9

### Problem 22.6

(a)

Consider two cases: one case in which  $R_2$  does not have any unsatisfied sets at time  $t$ , and another case in which  $R_2$  *does* have an unsatisfied set at time  $t$ .

Case 1: If  $R_2$  does not have any unsatisfied sets at time  $t$ , then by definition all of its vertices in  $S_1$  are connected by a tight path. Since the vertices in  $S_1$  for  $R_1$  are a subset of the vertices in  $S_1$  for  $R_2$ , any vertices  $u, v \in S_1$  connected by a tight path in  $R_1$  at time  $t$  must also be connected by a tight path in  $R_2$ .

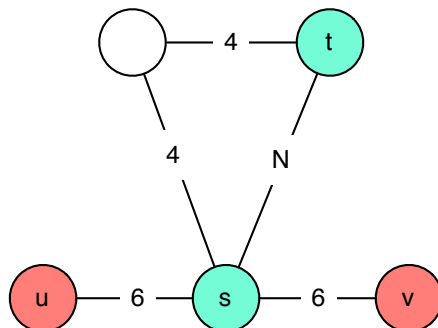
Case 2: Next, consider the case where  $R_2$  has an unsatisfied set at time  $t$ . For this case, we will prove a claim stronger than the original one: if  $R_2$  has an unsatisfied set, then any edge  $e \in E$  that is tight in  $R_1$  is also tight in  $R_2$ . If this claim is true, then any tight path connecting  $u, v \in S_1$  for  $R_1$  must also connect  $u, v \in S_1$  for  $R_2$ .

Assume the claim is false, so that it's possible for there to be a tight edge in  $R_1$  but not in  $R_2$ . The only way for an edge to be tight in  $R_1$  but not in  $R_2$  is if, at some point between 0 and  $t$ , one of the nodes touching edge  $e$  was in an active set in  $R_1$  but not in  $R_2$ .

Initially,  $R_1$  and  $R_2$  contain the same active sets, except that  $R_2$  has one additional active set. So any node initially in an active set for  $R_1$  is also in an active set for  $R_2$ . This means that any edge that feels a dual after the first step in  $R_1$  also feels a dual in  $R_2$ .

Because  $R_2$  has an unsatisfied set, none of its active sets will stop growing. Thus, although the additional vertex in  $R_2$  can cause two active sets to be merged together, it cannot cause any vertex to no longer be in an active set. Thus, at any point between 0 and  $t$ , any vertex in an active set in  $R_1$  is also in an active set in  $R_2$ , so it can't be possible for there to be a tight edge in  $R_1$  but not in  $R_2$ . Therefore, there can't be a tight path for  $u, v \in S_1$  for  $R_1$  but not  $R_2$ .

(b)



The figure gives an example of run  $R_1$ , where  $u$  and  $v$  are in  $S_1$ ,  $s$  and  $t$  are in  $S_2$ , and  $k = 2$ . Let  $N$  in the figure be an arbitrarily large number. At time  $t = 3$ ,  $u$  and  $v$  will be connected by a tight path. However, if run  $R_2$  is the same as run  $R_1$  except that the white vertex was also in  $S_2$ , then all vertices in  $S_2$  would be connected at time  $t = 2$ , and neither edge  $(u, s)$  nor  $(s, v)$  would be tight at time  $t = 3$ . Thus, we have a counterexample for the previous claim for a case when  $k > 1$ .