

High-Level Design Issues

CSCI2340: Software Engineering of Large Systems Steven P. Reiss



DON'T ALWAYS WORK WELL TOGETHER



# High-Level Design

- Last time we talked about high level design
  - Things to look for
  - Thinking about components
  - Noted that the component INTERFACES were the design
- We talked about selecting component
  - For the components
- Next, we need to define their interfaces
  - Messy to do in UML; easier to do in a language
- This is a continuation
  - More things to consider in the design
  - Looking ahead to using the design
- Topics
  - Language-based representations for defining component interfaces
  - Message-based interfaces
  - Choice of language (for implementation, but we use it in the design)
  - Using external (open-source and other) code, packages and systems
  - Designing for concurrency



## Language-Based Interface-Based Design

- Each component is represented by a (Java) interface
  - Component represents a class
  - Single interface file for a component
  - The whole design is represented as interfaces in Java
- Data passed between components is defined with an interface
  - Possibly defined as inner interface to component
  - Possibly with its own component / interface
  - Everything shared only through these interfaces
- Each call-back from a component is an interface
  - Defined as inner interface to component
  - More consistent than using function pointers, easier to extend
- Interfaces defined in a common package
  - Separate from implementation packages
  - Might later be augmented with common code (e.g., logging)
- Examples
  - S6/common, Catre/catre, Rose/root, Eclipse (IClassFile, ...), SHORE



## Interface-Based Design for SHORE

#### public interface ShoreModel {

Collection<ModelSwitch> getSwitches(); Collection<ModelSignal> getSignals(); Collection<ModelSensor> getSensors(); Collection<ModelBlock> getBlocks(); Collection<ModelBlock> getEngines(); void addModelCallback(ModelCallback cb); void removeModelCallback(ModelCallback cb); void removeModelCallback(ModelCallback cb); void sensorChanged(ModelSensor s); void sensorChanged(ModelSensor s); void signalChanged(ModelSignal s); void blockChanged(ModelBlock b); void engineChanged(ModelEngine e);

```
}
```

enum ModelSensorState { OFF, ON, UNKNOWN }

```
interface ModelSensor {
    ModelBlock getBlock();
    ModelSensorState getSensorState();
}
```

```
enum ModelSwitchState { N, R, UNKNOWN }
```

```
interface ModelSwitch {
   ModelSensor getNSensor();
   ModelSensor getRSensor();
   void setSwitch(ModelSwitchState s);
   ModelSwitchState getSwitchState();
}
```

```
enum ModelSignalState { OFF, GREEN, YELLOW, RED }
interface ModelSignal { ... }
enum ModelBlockState { EMPTY, INUSE, UNKNOWN }
interface ModelBlock { ... }
interface ModelEngine { ... }
```

// end of interface ShoreModel



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# Interface-Based Design for SHORE

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| <pre>visi setser(fictoring: sec, fictoring: fictoring: sec, fictoring: fictorin</pre> |   | void setsignal(ifacesignal sig, shoresignalstate set);   |                            |   |  |   |   |   |   |   |                                |
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| {       ////////////////////////////////////   |   | edub brownb.ck-sprb-shoreb.HackBlerket.<br>public interface IfaceSafety extends IfaceConstants<br>{<br>f<br>f<br>f<br>f<br>f<br>f<br>f<br>f<br>f<br>f<br>f<br>f<br>f |                            | eTrains   |  | <pre>public interface IfaceSensor extends {     IfaceSwitch getSwitchN(); }</pre> |   | faceConstants   | <pre>public interface IfaceEngine {</pre> |   |                                |
| boolean setSuitch (fraceSuitch sv, ShoreSuitchState state);<br>  |   |  |                            | in(String n   | iame); 🛛   |   |   | _   |   | IfaceBlock getEngineBlock():  |                                |
| Indecending findTrain(String name);       a       indecending etswitch();       a       indecending etswitch();       bolean istergen();         indecending etswitch();       indecending etswitch();       indecending etswitch();       bolean istergen();       bolean istergen();         indecending etswitch();       indecending etswitch();       indecending etswitch();       bolean istergen();         indecending etswitch();       indecending etswitch();       indecending etswitch();       bolean istergen();         indecending etswitch();       indecending etswitch();       indecending etswitch();       indecending etswitch();         indecending etswitch();   |   | <pre>boolean setSwitch(IfaceSwitch sw,ShoreSwitchState state);<br/>boolean setSignal(IfaceSignal ss ShoreSignalState state);</pre>                                   |                            |   |  |   |   |   |   | <pre>IfaceBlock getCabooseBlock(); Collection<ifaceblock> getAllBl</ifaceblock></pre> |                                |
| > // end of interface IfaceSafety       ) // end of interface IfaceSafety  |   | IfaceEngine findTra:   |                            |   | ne); 🛛 🗷   | IfaceSwitch getSwitchR();   |   |   |   | <pre>void enterBlock(IfaceBlock blk);<br/>void exitBlock(IfaceBlock blk);</pre>       |                                |
| ifaceEngine findTrain(SocketAddress sa);       a       ifaceEngine findTrain(SocketAddress sa); <td></td> <td>} // end of interface IfaceSafety</td> <td></td> <td></td> <td></td> <td colspan="3"></td> <td></td> <td>hosloss isStoned():</td> <td></td>  |   | } // end of interface IfaceSafety  |                            |   |  |   |   |   |   | hosloss isStoned():   |                                |
| ?       Description       Resource       Line       Software       Softwar  |   | IfaceEngine findTrai   |                            |   | ess sa); 🛛   | IfaceConnection getConnection();  |   |   | Ē   | <pre>boolean isEmergencyStopped();</pre>  |                                |
| ?     Description     Resource     InaceBiock (TrainCallback cb);     a     InaceBiock getBiock();     a     void startTrain();     socketAddress getEnglineAddress();       void startTrain();     socketAddress sol;     a     inaceBiock getBiock();     a     void startTrain();   | • ····<br>Collection <ifaceeng< td=""><td>e&gt; getAllEn</td><td>gines();</td><td colspan="3"></td><td></td><td><pre>void stopTrain();<br/>void emergencyStopTrain();</pre></td><td></td></ifaceeng<> |  |                            | e> getAllEn   | gines();   |   |   |   |   | <pre>void stopTrain();<br/>void emergencyStopTrain();</pre>                           |                                |
| Image: constraint of the constr                        |   |  |                            |   |  | IfaceBlock getBlock();  |   |   | ľ   | volu staftiräin();  |                                |
| P       Description       Resource       Line       void addTrainCallback(TrainCallback cb);       void addTrainCallback cb);       void addT   | 7         Description         Resource         Line   |  |                            | Socket(Ifac   | eEngine engine,SocketAddress sa);                                      | <pre>ShoreSensorState getSensorState();</pre>                                     |   |   | 9   | SocketAddress getEngineAddress()  | )                              |
| void addTrainCallback (TrainCallback cb); za void setSensorState (ShoreSensorState state); za void ringBell();   |   |  |                            |   | -  |   |   | 2   |   | <pre>void setSpeed(int speed);</pre>  |                                |
|  | void addTrainCallbac  |  |                            | (TrainCallb   | ack cb);   | void setSensorState(ShoreSensorState state); void ringBell();                     |   |   | void blowHorn();<br>void ringBell();      |   |                                |
|  |   |  |                            |   |  |   |   |   | ····                                      |   |                                |
| Called inst for a final file inst for a file ins       |   |  |                            | ack/TrainCa   | llback_cb).  | FolloctionelfaceSignals antSignals():   |   |   |   | // end of interface itad  |                                |

Code Bubbles (Eclipse) for shore

## Advantages of Interface-Based Design

- Provide a solid understanding of the components
  - And their interactions before they are written
  - In the target language, in a single location (package)
- Can explore interface possibilities
  - Experiment with different alternatives, methods, interfaces
  - Easy to edit, change: no real commitment at this point
  - More familiar than working in UML
- Provide a basis for implementation of the components
  - Result becomes part of the system
  - Maintained as the system evolves
- Provide a clean separation between components in the implementation
  - All interactions between components are through the interfaces
  - Can compile the rest in almost any order
- Provide a location for documenting the design
  - Javadoc of the interface
- Can provide dummy / stub implementations (implementing the interface)
- Can write test cases (against the interfaces)
- Consistent approach to design (all object-oriented interfaces)



## Disadvantages of Interface-Based Design

- Commits the choice of language
  - Not all interfaces are language-based
  - Can rewrite the interface in actual target language (not that much to do)
- Can make implementation a bit messier
  - Trivial classes, public methods
  - Need factory methods which might require reflection
  - Need to cast interface to implementation class internally
  - Returning collection of interfaces from collection of implementations is non-trivial in Java
  - Interface for messages requires corresponding code
- Might require a hierarchy of interfaces
  - To add functionality without changing existing code
    - JcompFile, JcompExtendedFile
- Changing an interface can affect many components
  - Especially call-back interfaces
  - Default methods in Java now make this a little easier
- Changing the implementation might need to change some interfaces
  - Even if backward compatible
- Interfaces will grow over time
  - Can become overly complex with time design will no longer be as clean



## Façade-Based Design



- A component is represented by a small set of public classes and interfaces
  - Ideally a single class that delegates most of the work
    - This represents the interface to the component
  - And a set of interfaces or abstract classes exposing passed data and callbacks
  - All other classes in the package are non-public
    - The bulk of the work of the component is done in these classes
  - Component implemented in a single package or module
- Example: Code Bubbles
  - Core (3 packages) includes a small set of public classes (< 20)
  - Each component outside core has Constants interface and Factory class
    - Constants defines interfaces for shared data, enumerations, callbacks, ...
  - All access is through these, not implementation classes
  - Other interfaces can be defined if needed (generally in Constants)
  - Standard interface to factory (setup/initialize)

## Façade-Based Design for SHORE

|  | Code Bubbles (Eclipse) for shore   |   |   |  |  |
|--|--|---|---|--|--|
| package edu.brown.cs.shore.view;<br>import edu.brown.cs.shore.ifaces.ShoreModel; | All Rights Reserved       */         *       */         *       */         *       */         *       */         *       */         *       */         *       */         *       */         *       */         *       */         *       */         *       */         *       */         */       */         */       */         */       */         */       */         */       */         */       */         */       */         */       */         */       */         */       */         */       */         */       */         */       */         */       */         */       */         */       */         *   | <pre>ModelFactory <file>  if (the_factory = null) {     the_factory = null delFactory();     return the_factory;    </file></pre>   | there:edu.brown.cs.spr.shore<br>⊕ @docs |  |  |
| public class ViewFactory   | <pre>* commercial product is hereby granted without fee, provided that the * * above copyright notice appear in all copies and that both that * copyright notice and this network of the copyright notice appear is a second that the second the s</pre> | public void resetModel()  |   |  |  |
| <pre>public ViewFactory(ShoreModel model) { }</pre>                              | * copyright notice and this permission notice appear in supporting *<br># documentation, and that the name of Brown University not be used in *<br># advertising or publicity pertaining to distribution of the software *<br># without specific, written prior permission. *<br># BROWN UNIVERSITY DISCLAIMS ALL WARRANTIES WITH REGARD TO THIS *<br>* SOFTWARE, INCLUDING ALL IMPLED WARRANTIES OF MERCHANTABILITY AND *   | <pre>// if ic has changed, reread the model file<br/>// if i[ic has changed, reread the model file<br/>// run initialization sequences to find states<br/>// check connectivity<br/>// try to locate trains<br/>}</pre> |   |  |  |
| <pre>public void startDisplay() { }</pre>  | * FITNESS FOR ANY PARTICULAR PURPOSE. IN NO EVENT SHALL BROWN UNIVERSITY *<br>BE LIABLE FOR ANY SPECIAL, INDIRECT OR CONSEQUENTIAL DAMAGES OR ANY *<br>DAMAGES WHATSOEVER RESULTING FROM LOSS OF USE, DATA OR PROFITS, *<br>* WHETHER IN AN ACTION OF CONTRACT, NEELIGENCE OR OTHER TORTIOUS *<br>ACTION, ARSISING OUT OF OR IN CONNECTION WITH THE USE OR PERFORMANCE *<br>* OF THIS SOFTWARE. *  | <pre>public void loadModel(File description)  model_file = description; Element xml = IvyXml.loadXmlFromFile(model_file);</pre>   |   |  |  |
| } // end of class ShoreModel   | *  | <pre>ShoreLog.log0("Loaded model: " + IvyXml.convertXmlToString(xml));      // load model from file      // setup all switches, signals, trains, sensors }</pre>  |   |  |  |
|  | ackage edu.brown.cs.spr.shore.model;   |   |   |  |  |
|  | ublic interface ModelConstants   | /*************************************  |   |  |  |
|  | Interface ModelSensor { }  | /*************************************  |   |  |  |
|  | nterface ModelTrain { } z  | ₹<br>return new ArrayList⇔();   |   |  |  |
|  | nterface ModelSignal { }   | }<br>public Collection≪HodelSignal> getSignals()<br>Ч<br>return new ArrayList⇔();<br>}  |   |  |  |
|  |  | public Collection-ModelSensor> getSernsors()  |   |  |  |
|  |  | return new ArrayList<>();   |   |  |  |
|  |  |   |   |  |  |



## Advantages of Façade-Based Design

- Good match to layered systems
  - A façade can represent a layer
- Good match to extensible-component systems
  - Components implemented directly
- No need for odd factory methods, easier to change
  - Components are the implementation
- Easier to extend by adding new components
  - Not as restricted as interface-based design



## Disadvantages of Façade-Based Design

- Harder to implement components in parallel
  - Need inner layers defined to compile & write the outer ones
- Not as clean a separation as interface-based design
- Can be tricky to achieve an implementation ordering
  - Linear order for compilation, dependencies
- No central description of the system
- More difficult to understand each component
- Interface mixed with implementation
  - Too easy to expose the implementation
  - Through the public methods of a component
  - Too easy to add new public methods & complicate the interface
- Tendency to avoid documentation



## Message-Based Interfaces

- Choose a messaging framework
  - Preferably use an existing one (JMF, Ros, ...)
  - HTTP: RESTful interfaces
  - Code Bubbles: mint
- Define a set of messages (and responses)
  - This is the interface
  - Akin to defining function or method calls (documentation)
  - Definition should include expected behavior
  - Definition should include error behavior
  - Definitions should be explicit (formats, options, etc.)
- Easy to allow optional parameters on messages
- Must be documented
  - Can be a set of constants in an interface file
  - Can be represented by a class that handles the messaging (BumpClient)



### Message Interface in SHORE

| dub brownb csb sprb shoreb networkb NetworkLocoFiMessagesb |        |   |  |  |  |  |  |
|--|--------|---|--|--|--|--|--|
| interface NetworkLocoFiMessages                            |        |   |  |  |  |  |  |
| {  |        |   |  |  |  |  |  |
| B  |        |   |  |  |  |  |  |
| <pre>byte [] LOCOFI_START_ENGINE_CMD = -</pre>             | {0×00, | 0×01};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_STOP_ENGINE_CMD = .</pre>              | {0x00, | 0×00};  |  |  |  |  |  |
| byte [] LOCOFI_FWD_DIR_CMD =                               | {0x01, | 0×00};  |  |  |  |  |  |
| byte [] LOCOFI_REV_DIR_CMD =                               | {0x01, | 0x01};  |  |  |  |  |  |
| • •••  |        |   |  |  |  |  |  |
| <pre>byte [] LOCOFI_FWD_LIGHT_OFF_CMD = -</pre>            | {0x03, | 0×00};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_FWD_LIGHT_ON_CMD = -</pre>             | {0x03, | 0x01};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_FWD_LIGHT_BLINK_CMD = -</pre>          | {0x03, | 0x02};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_REV_LIGHT_OFF_CMD = -</pre>            | {0x04, | 0x00};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_REV_LIGHT_ON_CMD = -</pre>             | {0x04, | 0x01};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_REV_LIGHT_BLINK_CMD =</pre>            | {0x04, | 0x02};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_HORN_ON_CMD = ·</pre>                  | {0×05, | 0x03, 0x01};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_HORN_OFF_CMD = -</pre>                 | {0×05, | 0x03, 0x00};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_BELL_ON_CMD = .</pre>                  | {0x05, | 0x04, 0x01};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_BELL_OFF_CMD = .</pre>                 | {0x05, | 0x04, 0x00};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_RPM_REPORT_CMD = .</pre>               | {0x06, | 0x00};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_SPEED_REPORT_CMD = -</pre>             | {0×07, | 0x00};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_QUERY_LOCO_STATE_CMD = -</pre>         | {0×08, | 0x00};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_CONNECT_SSID_CMD = -</pre>             | {0×09, | 0×00};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_DISCONNECT_SSID = -</pre>              | {0×09, | 0x01};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_REBOOT_CMD = .</pre>                   | {0x0A, | 0x00};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_VERSION_CMD = .</pre>                  | {0×0B, | 0x00};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_HOSTNAME_CMD = -</pre>                 | {0x0C, | 0x00};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_SETTINGS_READ_CMD = -</pre>            | {0×0D, | 0x00};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_SETTINGS_WRITE_CMD = -</pre>           | {0×0D, | 0x01};  |  |  |  |  |  |
| hyte [] LOCOFT SET SPEED (MD =                             | {0x0F  | AVAA AVAA}.   |  |  |  |  |  |
| byte [] LOCOFT HEARTBEAT ON CMD =                          | {0x0E  | ava1};  |  |  |  |  |  |
| byte [] LOCOFT HEARTBEAT OFF (MD) =                        | {0x0F  | 0,00];  |  |  |  |  |  |
| byte [] LOCOFT FACTORY RESET CMD =                         | {0x10. | 0x00}:  |  |  |  |  |  |
| byte [] LOCOFT OUERY ABOUT LOCO CMD =                      | {0x11. | 0x00}:  |  |  |  |  |  |
| byte [] LOCOFT EMERGENCY STOP CMD =                        | {0x12. | 0x00}: //the second argument 00 is for stop             |  |  |  |  |  |
| byte [] LOCOFI EMERGENCY START CMD =                       | {0x12. | 0x01: //the second argument 01 is for resume            |  |  |  |  |  |
| byte [] LOCOFT GET CONSIST CMD =                           | {0x13. | 0×001:  |  |  |  |  |  |
| byte [] LOCOFT CREATE CONSTST LEAD CMD =                   | {0x14. | 0x00}:  |  |  |  |  |  |
| byte [] LOCOFT CREATE CONSIST HELPER CMD =                 | {0x14. | 0x01}:  |  |  |  |  |  |
| byte [] LOCOFI DELETE CONSIST CMD =                        | {0x15. | 0x00}:  |  |  |  |  |  |
| byte [] LOCOFI SPEED TABLE READ CMD =                      | {0x16. | 0×00};  |  |  |  |  |  |
| byte [] LOCOFI SPEED TABLE WRITE CMD =                     | {0x16. | 0x01};  |  |  |  |  |  |
| byte [] LOCOFI SPEED TABLE UPDATE CMD = ·                  | {0x16. | 0x02};  |  |  |  |  |  |
| byte [] LOCOFI SPEED TABLE DELETE CMD =                    | {0x16. | 0x03}:  |  |  |  |  |  |
| byte [] LOCOFI MUTE VOLUME CMD =                           | {0x17, | 0x00}: //only applicable for sound upgradeable modules  |  |  |  |  |  |
| byte [] LOCOFI UNMUTE VOLUME CMD =                         | {0x17, | 0x01}: //only applicable for sound upgradeable modules  |  |  |  |  |  |
| byte [] LOCOFI HIGH FREQ OP OFF CMD =                      | {0x18, | 0x00};  |  |  |  |  |  |
| <pre>byte [] LOCOFI_HIGH_FREQ_OP_ON_CMD = -</pre>          | {0x18, | 0x01};  |  |  |  |  |  |
| (//Ax7C) is received for messages from lead                | to bol |   |  |  |  |  |  |
| byte [] LOCOFI_HELPER_CMD_SS =                             | {0x7C, | 0x00}; //stop for safety; third byte contains OFF or ON |  |  |  |  |  |
|  |        |   |  |  |  |  |  |
| <pre>//{0x7D} is reserved for (asynchronous) ack</pre>     | messag | ges from helper to lead                                 |  |  |  |  |  |
| byte [] LOCOFI_HELPER_ACK_CMD_ES =                         | {0x7D, | 0x00}; //engine state; third byte contains the state    |  |  |  |  |  |
|  |        |   |  |  |  |  |  |
| } // end of interface NetworkLocoEiMer                     | ceanee |   |  |  |  |  |  |

| edu▶br   | own▶ cs▶ spr▶ shore▶ r | ietw | /ork►Ne | tworkControlMess | sages | •                                     | 2 |  |
|--|------------------------|------|---------|------------------|-------|---------------------------------------|---|--|
| interface NetworkControlMessages { Click to begin search starting here } |                        |      |         |                  |       |                                       |   |  |
|  |                        |      |         |                  |       |                                       |   |  |
| byte   | CONTROL_HEARTBEAT      | =    | (byte)  | 0x0f;            | 11    | turn on/off heartbead                 |   |  |
| byte   | CONTROL_REBOOT         | =    | (byte)  | 0x0a;            | 11    | restart                               |   |  |
| byte   | CONTROL_QUERY          | =    | (byte)  | 0x40;            | 11    | ask for id                            |   |  |
| byte   | CONTROL_RESET          | =    | (byte)  | 0x41;            | 11    | reset sensors, etc.                   |   |  |
| byte   | CONTROL_SYNC           | =    | (byte)  | 0x42;            | 11    | ask for settings of sensors, switches |   |  |
| byte   | CONTROL_SETSWTICH      | =    | (byte)  | 0x43;            | 11    | set switch to state                   |   |  |
| byte   | CONTROL_SETSIGNAL      | =    | (byte)  | 0x44;            | 11    | set signal to stat                    | 2 |  |
| byte   | CONTROL_DEFSENSOR      | =    | (byte)  | 0x45;            | 11    | assoc sensor with switch state        | 2 |  |
| byte   | CONTROL_SETSENSOR      | =    | (byte)  | 0x46;            | 11    | note sensor state                     |   |  |
| byte   | CONTROL_DEFSIGNAL      | =    | (byte)  | 0x47;            | . 11  | set type of signal                    | N |  |
|  |                        |      |         |                  |       |                                       |   |  |
| byte   | CONTROL_ID             | =    | (byte)  | 0x50;            | 11    | this is our ID                        |   |  |
| byte   | CONTROL_SENSOR         | =    | (byte)  | 0x51;            | 11    | sensor set to value                   |   |  |
| byte   | CONTROL_SWITCH         | =    | (byte)  | 0x52;            | 11    | switch set to value                   |   |  |
| byte   | CONTROL_SIGNAL         | =    | (byte)  | 0x53;            | 11    | signal set to value                   |   |  |
| byte   | CONTROL_ENDSYNC        | =    | (byte)  | 0x54;            |       |                                       |   |  |
| byte   | MESSAGE_ALL            | =    | 0×10;   |                  |       |                                       | 2 |  |
| byte   | MESSAGE_0FF            | =    | 0x0;    |                  |       |                                       | 2 |  |
| byte   | MESSAGE_ON             | =    | 0x1;    |                  |       |                                       |   |  |
| byte   | MESSAGE_UNKNOWN        | =    | 0x2;    |                  |       |                                       |   |  |
| byte   | MESSAGE_N              | =    | 0x0;    |                  |       |                                       |   |  |
| byte   | MESSAGE_R              | =    | 0x1;    |                  |       |                                       | N |  |
| byte   | MESSAGE_RED            | =    | 0x1;    |                  |       |                                       | Z |  |
| byte   | MESSAGE_GREEN          | =    | 0x2;    |                  |       |                                       | Z |  |
| byte   | MESSAGE_YELLOW         | =    | 0x3;    |                  |       |                                       | Z |  |
| byte   | MESSAGE_SIG_RG         | =    | 0x0;    |                  |       |                                       | 2 |  |
| byte   | MESSAGE_SIG_RGY        | =    | 0x1;    |                  |       |                                       | Z |  |
| byte   | MESSAGE_SIG_RG_ANO     | DE   | = 0x2;  |                  |       |                                       | N |  |
| byte MESSAGE_SIG_RGY_ANODE = 0x3;  |                        |      |         |                  |       |                                       |   |  |
|  | 11                     | £    | - N     |                  |       |                                       |   |  |

} // end of interface NetworkLocoFiMes

9/24/24

## Pros and Cons of Message Interfaces

- Easy to change, augment, add new
- Limited applicability
  - Between-process, more difficult within a process
    - Use callbacks within a process
  - Handles front-back end in web/mobile applications
- Handling concurrent messages and replies can be messy
  - Replies tend to be asynchronous
  - Replies can always fail
  - Can/should component process multiple messages at once
    - For separate users
    - For the same user
- Tendency to avoid documentation
- Requires a messaging architecture



## Languages for Large Systems

- I've used Java for my examples
  - Right now for language-based design, later for coding
  - Object-oriented languages work for large systems
    - Provide nice localized information hiding
    - Much cleaner than procedural or functional representations: C with ADTs (Classes)
    - A good way of thinking about components (interface vs implementation)
    - Consistent approach (everything is done with objects)
  - Interfaces are a natural part of the language
  - Packages provide a convenient way of representing a component
  - Common interface package provides a representation of the design
- Other languages can be used as well (but often not quite as nicely)
  - C# is roughly equivalent to Java
  - C++ can be used if careful (effectively define interfaces; use safe pointers)
  - Other modern languages (Go, Rust)
  - Web & mobile languages (Dart, Swift, Android Java, JavaScript, TypeScript)
  - Façades & interfaces can be created in any language
    - But can be more difficult to hide the implementation
    - Need control of visibility, import and export (as part of the language)
- Need to understand what you want from the programming language
  - To choose the most appropriate language for your application



## Large-Scale PL Requirements

#### • Language must be supported over time

- Relatively stable and upward compatible
- Language evolves to match current programming style and issues
  - Can be good or bad language can get too complex
- Libraries and other components are rich, stable, and supported
- IDEs and debugging are well-supported
  - Coding, navigating, discovery, debugging, compiler feedback
- Avoid extensions, especially non-standard ones
- Language must be compiled (catch bugs early)
  - With immediate error feedback from the IDE
- Language must be strongly typed
  - Types are a form of documentation and checking
  - Types ensure interfaces are used correctly
  - Typing moves error to compile time rather than run time
- Language must be modular (avoid name conflicts)
- Language must support objects, classes, and interfaces
  - Object-oriented design supports the needed abstractions
  - Objects provide information hiding
  - Large systems are best modeled in an object-oriented fashion



## Large-Scale PL Requirements Continued

- Language should be easy to read
- Language must support information hiding
  - Private or local data & code
  - Individual modules with import/export
  - Different levels of access
- Language should support concurrency
  - Explicitly or implicitly
  - Preferably in the language, not in a library
- Language should support documentation
- Language should be compatible with external libraries and systems
  - That you will or might need for your application
  - Most common libraries have APIs for a variety of languages, but not all
- Language must support your system
  - Messaging
  - Where it can run (bare hardware, browser, OS, mobile platforms, ...)

## Large-Scale PL Requirements Continued

- Language should be one your team is comfortable with
  - Learning to use a language effectively can take from 1 month to a year
- Language should make it easy to write safe programs
  - Safe memory [garbage collection] (Java, C#)
  - Help check for null pointers (dart)
  - Help check for memory ownership (rust)
- What doesn't matter
  - Brevity (this can get in the way of readability)
  - Ease of writing initial code
  - Efficiency of implementation
- What language should you use on your project???
  - It should meet these constraints
    - Choice of language is important in long-lived, large systems
  - Put the decision off as long as possible to better understand your needs
  - Different languages might be used in different components

## Multilingual Systems

- Common for large software systems today
  - Each process can be in its own language
    - Message systems usually support multiple languages
    - HTTP messaging works everywhere
  - Can mix multiple languages within a process
    - Trickier, not recommended, but can be done
  - Web applications generally imply different languages
    - Front end versus back end
  - Native phone apps generally imply different languages
    - Different operating systems; front end versus back end
- Choose most appropriate language for each component
  - But try to be consistent
  - Mixing has costs and risks
  - Develop consistent naming conventions across the project



## Designing Around What Exists

- Don't build everything from scratch
  - Too much work, room for error, maintenance, risk
  - Keep things simple
- Reuse the work of others where practical
  - Where it simplifies your efforts
    - Now and in the future
  - Where the benefits outweigh the costs and risks
    - There are always costs
    - There are always risks



## Standardized Code

- Lots of "standardized" code exists
  - Libraries that have evolved over time
  - Common subsystems that are widely used
  - Subsystems and libraries that are actively maintained
  - Interfaces to existing frameworks
    - OpenCV, SmartThings, ChatGPT, MongoDB, SQL, ...
- These are typically (but not always)
  - Well-debugged and tested
  - Documented
  - Maintained by others (less work for you)
  - Generally, with a well-thought-out interface (API)



### **Common Domains**

- Some aspects of programming occur over and over
- In-House Anticipated Expertise Future Requirements Domain Analysis Marketing Existing Material Requirement Common Functions Reusable "Build" Products Structure System Specification Classes Map to and Existing Risk Objects Hardware/Software Analysis and Documentation

- Low level: Data structures, Algorithms, Properties
- High level: Databases, Machine learning
- Lots of others that aren't as common, but still exist
- In these domains, it is generally better to use existing code
  - Complex, tricky implementations
  - Existing tools allow for evolution, increasing complexity
  - Well-understood
  - Standard interfaces

#### Databases

- Anytime you need reliable, permanent data storage
  - Long or short term, simple or complex
- Use a database system
  - Difficult to corrupt
  - Might need to be shared or distributed
- Not difficult to use
  - After you've done it once
- Not slower than doing something specific for your system
  - Separate process, optimized, good error checking and handling
  - Extensible to handle evolution, maintenance
  - Writing to socket as fast or faster than writing to disk
- Easy to migrate to more robust solutions as needed
  - [SQLite] => MySQL => Commercial system (Oracle, DB2, SQL Server)
  - MongoDB => Distributed MongoDB
- But
  - Another point of failure, porting, and distributing software, ...

![](_page_22_Picture_17.jpeg)

## Search Tools

- Search capabilities
  - Search over multiple documents
    - Indexed by keyword or other features (e.g., code patterns)
    - Intelligent handling of multiple keywords, occurrences, logic, ...
  - Building and maintaining an index
- Libraries exist for this purpose
  - Lucene as a general (open-source, extensible) library
  - Google search licensed for a particular domain or application

![](_page_23_Figure_9.jpeg)

## Machine Learning

#### Lots of machine learning algorithms

- Different domains require different approaches
- Standard, tested implementations available
- Use a standard ML library if your application uses ML
  - Unless you are researching ML
  - WEKA, SPARK, and others
  - Often want to run this as a separate process
  - API interfaces to LLMs (ChatGPT, Bard, ...)
- Similar domains
  - Computer Vision (OpenCV)
  - Speech Generation and Recognition

![](_page_24_Picture_12.jpeg)

## **Other Common Applications**

- Math Packages
  - LinPack, Array manipulation, Differential Equations
- Cryptography
  - Very hard to write safe code here let someone else do it
- Web Scraping
  - Jsoup, Beautiful soup, ...
- Java Editor framework
- Node packages (express,...)
- Html plugins (jQuery,...)

![](_page_25_Figure_10.jpeg)

## High-Level Design

- Reuse as much as possible
  - Within a company, often reuse frameworks, libraries, code
  - Develop an internal library (Ivy)
  - But balance benefits, costs, and risks
- Benefits
  - Cost to implement yourself
  - Cost to maintain and evolve
- Costs
  - Cost to learn (which can be high)
  - Cost to adapt the external code to your code
  - Cost to distribute (different licensing models)
  - Cost to license
  - Might skew or disrupt an otherwise clean design
    - Might not fit into your design

![](_page_26_Picture_15.jpeg)

## **Risks with External Code**

- Might need to commit the whole application
  - Apache collections
- Might have other dependencies
  - Use Apache logger
  - Lots of other libraries might be pulled in
  - Different versions of other libraries, Java, JUnit, ...
- Might evolve in a way incompatible with your application
- Might have bugs or security flaws
- Might not be maintained (lose support)
- Might not be well documented (difficult to use) [this is typical]
- Might not be a good fit for your needs
- IP rights might become problematic
- Might make distribution (both source and binary) difficult

![](_page_27_Picture_14.jpeg)

# Designing for Concurrency

#### • Goals

- Make best use of today's hardware
  - Multiple cores
  - Networks of computers (cloud)
- Covering idle time
  - Most time is spent waiting (UI, I/O operations)
- Simplicity
  - Independent things can be independent: processes, sockets
- A lot of this is implementation and comes later
  - But several factors affect high-level design as well

![](_page_28_Picture_11.jpeg)

## Concurrency: Multiple Processes

#### Independent processes that communicate

- Might run and read the result
- Might be message send and response
- This is the easiest to design and code
  - Each process is self contained
  - Limited interaction => limited chance for concurrency problems
    - But not non-zero (all the problems still exist)
  - Well-defined interactions
  - cpp, asm and the C compiler, Code Bubbles, weka in hump, sort

![](_page_29_Figure_10.jpeg)

## Concurrency: Background Tasks

- Use threads to support long-term work
  - Don't access the result until it is ready (futures)
  - Threads are independent
  - Use futures if they are available and work well in the language
  - Use thread pools to handle disparate work within a system; not separate threads
  - Examples: eclipse indexing; bubbles syntax fixing, search, ...
- Use threads to support long-term I/O
  - Sockets:
    - Thread to monitor server socket
    - Thread to monitor each client socket
  - Other I/O (COSE search, crawler)
- Most of this is in the implementation, not the design
- Non-threaded models (e.g., JavaScript, Dart)
  - Hide the threads & pools with asynchronous calls & futures
  - But they are still there

LlTasks.Where(w unt() == 0) = new BackgroundTaskBuil ame = "ToastTask"; TaskEntryPoint = "tagur.Serv SetTrigger(new PushNotificat

![](_page_30_Picture_18.jpeg)

## Concurrency: User Interface

- Swing/AWT thread handles all the UI issues (implementation)
  - Same for most UI packages
- Most of a user-centric program is reactive
  - User interface callbacks invoked in UI thread
  - But your callback code then will delay the UI thread
  - Don't want to do anything complex in response to the user
- View non-trivial actions as background tasks
  - Start up a new task for each action
  - Actions should be independent
  - Using thread pools or futures
- Actions affecting the UI
  - Should be done in the UI thread
  - Need to forward the actions to that thread

![](_page_31_Figure_14.jpeg)

# Concurrency: Algorithmic

- Concurrent Algorithms & Data Structures
- When a particular task is expensive
  - And the algorithm can be made concurrent
- Split a task into separate threads
  - Run those concurrently
  - Generally, need synchronization and sharing
- Think of this as implementation, not design
  - For design: if the task requires significant sharing
    - Think of it as one thread or process
  - Data structures provided by standard libraries

![](_page_32_Picture_14.jpeg)

## Concurrency in High-Level Design

- Start with a synchronous design
  - Easier to reason about, design at a high level
- Identify opportunities & needs for concurrency
  - What level of concurrency is appropriate
  - Concentrate first on separating processes
    - Other decisions are really implementation details
- Identify shared data structures
  - These complicate concurrency coding
  - Much easier to code if known in advance than to retrofit
  - Identify interfaces/classes that might be shared
    - Document these as thread safe or not thread safe
  - Isolate these in their own component
  - Identify other commonalities: database relations, etc.

![](_page_33_Figure_14.jpeg)

**Asynchronous vs Synchronous** Handling Concurrency in JavaScript

## Programming Homework

- Consider how you would modify your program to:
  - Rather that having properties on the screen determined either randomly or by user input, tie them to process properties.
    - On Linux you can look at /proc
    - On mac or Linux you can run ps and parse the input
    - On windows you can run tasklist
  - Examples of what can be done:
    - Ball size relates to log(memory size); Ball speed relates to CPU usage; Ball color relates to # files
    - Update every 1-10 seconds, adding/removing balls as needed
  - Issues
    - Number of balls (400-900 processes); asynchronous running of ps
- Consider also how to modify your program so that:
  - It runs in a circular window rather than a rectangular one
- Consider also how to modify your program to use multiple threads
  - Compute each ball's next position separately
- Write and submit a description of what would be changed for these cases
  - Don't do the changes just describe what you would have to do to your current application
  - How modular was your original design
  - How much could you reuse
- Due Thursday (canvas hand-in)

### **PROJECT Homework**

- Work on the high-level design
  - Choose appropriate target language(s) (based on criteria in lecture)
  - Think about interfaces in those languages
- Initial high-level design due Tuesday 10/8
  - Something that can be reviewed
    - Can be just a set of components
  - Hand in through canvas (one per team)
  - Not a final design

#### Next Tuesday 10/8 we'll have initial project presentations

- Describe what you are building
- Describe the high-level design
- 10 minutes (7 + 3 for questions)

## Research in High-Level Design

Creating high-level designs using LLMs or code search